Plug-and-play differential phase encoded measurement-device-independent QKD protocol

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Active stabilization systems are typically used in MDI implementations to ensure indistinguishability of photons from Alice and Bob, mainly in three dimensions: spectrum, polarization, and timing [1, 2]. These stabilization systems increase the complexity of QKD experiments. Plug-and-play architecture reduces the experimental complexity arising because of reference frame alignment between Alice and Bob [3, 4].

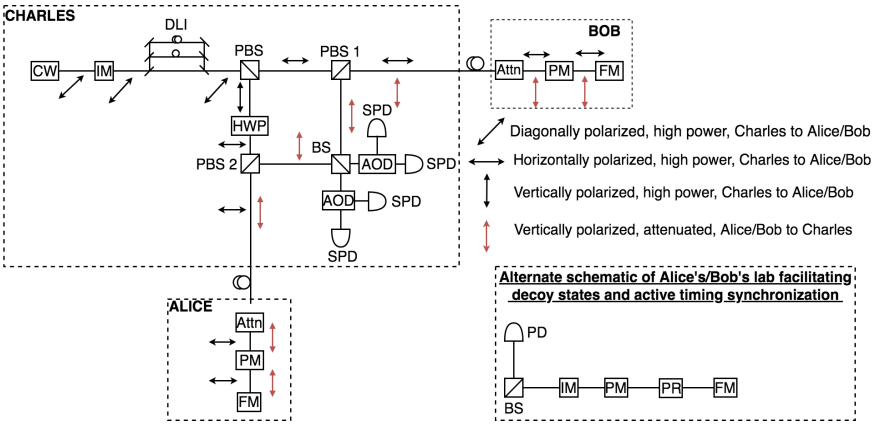

Fig. 1. Schematic of plug-and-play DPS MDI. CW = Continuous Wave laser, PC = Polarization controller, DLI = Delay Line Interferometer, PBS = Polarization Beamsplitter, HWP = Half-Wave Plate, BS = Beamsplitter, AOD = Acousto-Optic Deflector, SPD = Single-Photon Detector, IM = Intensity Modulator, PM = Phase Modulator, PR = Phase randomizer, FM = Faraday Mirror.

We have previously proposed a differential phase-encoded MDI protocol (DPS MDI), and using a decoy state analysis, we estimated the length of a secure channel for a weak coherent source (WCS) based implementation [5]. We use the WCS DPS MDI protocol for designing a plug-and-play DPS MDI scheme (see Fig. 1). In $n = 3$ DPS MDI, Alice and Bob encode their key information as phase difference between two time-bins. As these time bins are few nanoseconds apart, the quantum channel affects them in a similar way, thereby cancelling the effects of phase fluctuations. In other MDI protocols that use pulse-train, such as B92 MDI, Alice and Bob encode key information as phase of an individual pulse [6]. This applied phase gets affected by random fluctuations and results in higher QBER [7]. Note that, $n > 3$ DPS MDI would lead to increased complexity in key reconciliation scheme as well as in its implementation [8].

As Alice and Bob use independent lasers, an optical phase-locked loop (OPLL) is required to share a phase reference in MDI implementations. Using a single laser in our plug-and-play architecture removes the requirement of an OPLL. Further, Alice and Bob use independent delay lines to create three time-bins in DPS-MDI. The time-bins of Alice and Bob differ due to variations in their respective DLIs. Use of a single DLI in the plug-and-play scheme solves this issue. Hence, our plug-and-play differential phase encoding offers protection against random phase fluctuations along with ease of implementation.

References

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